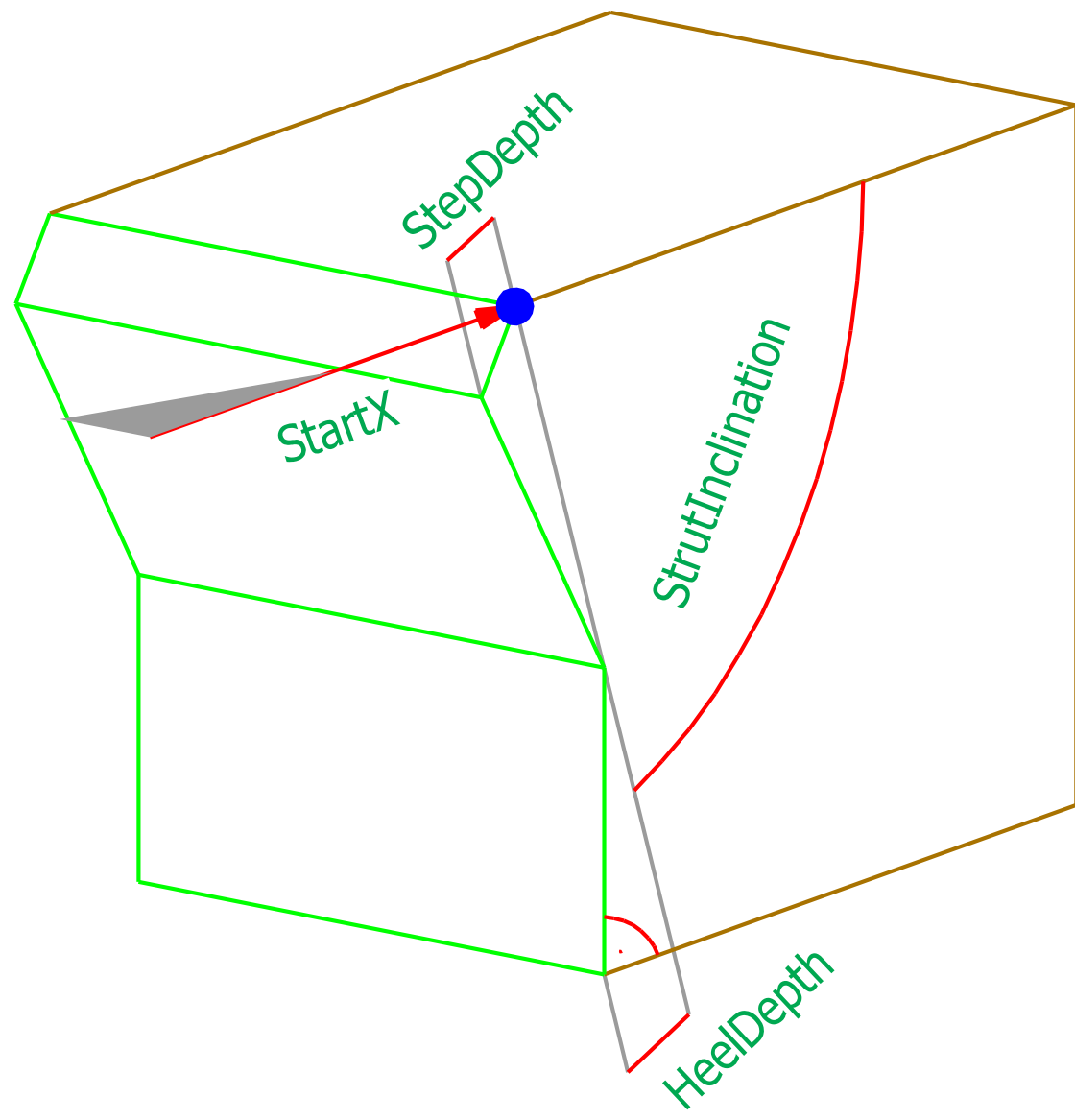


### StepJoint

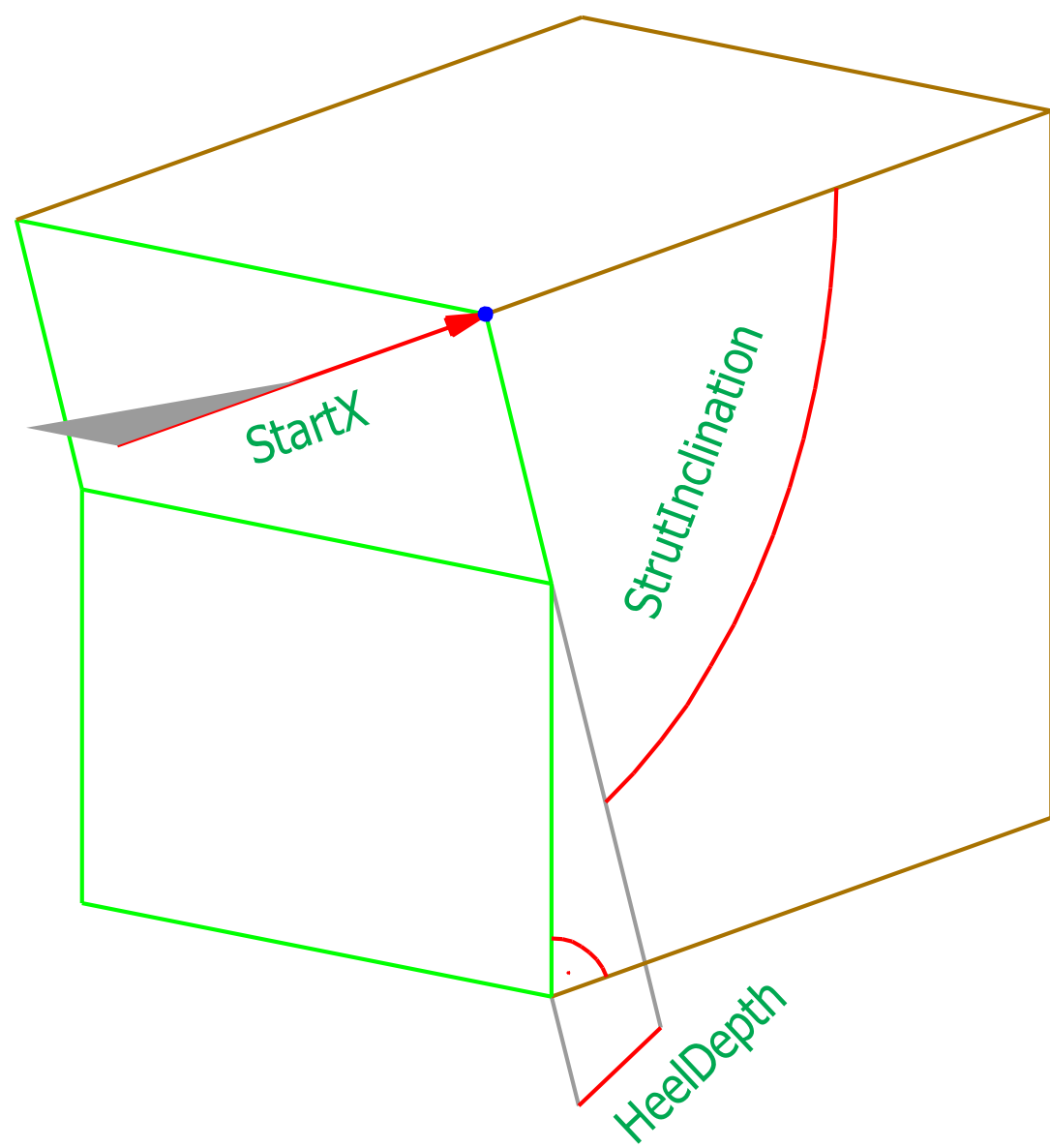
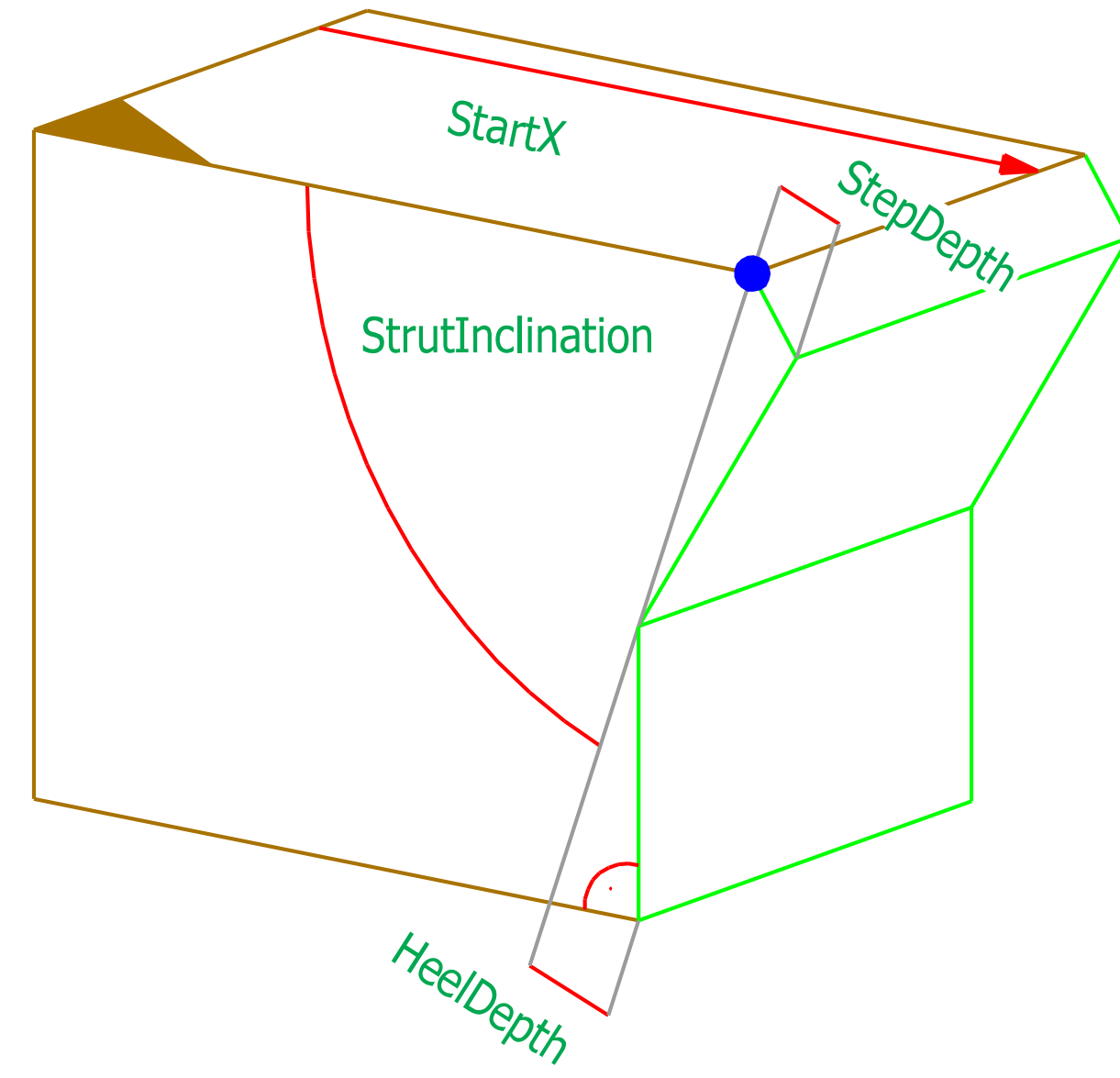
Orientation = start

Orientation = end

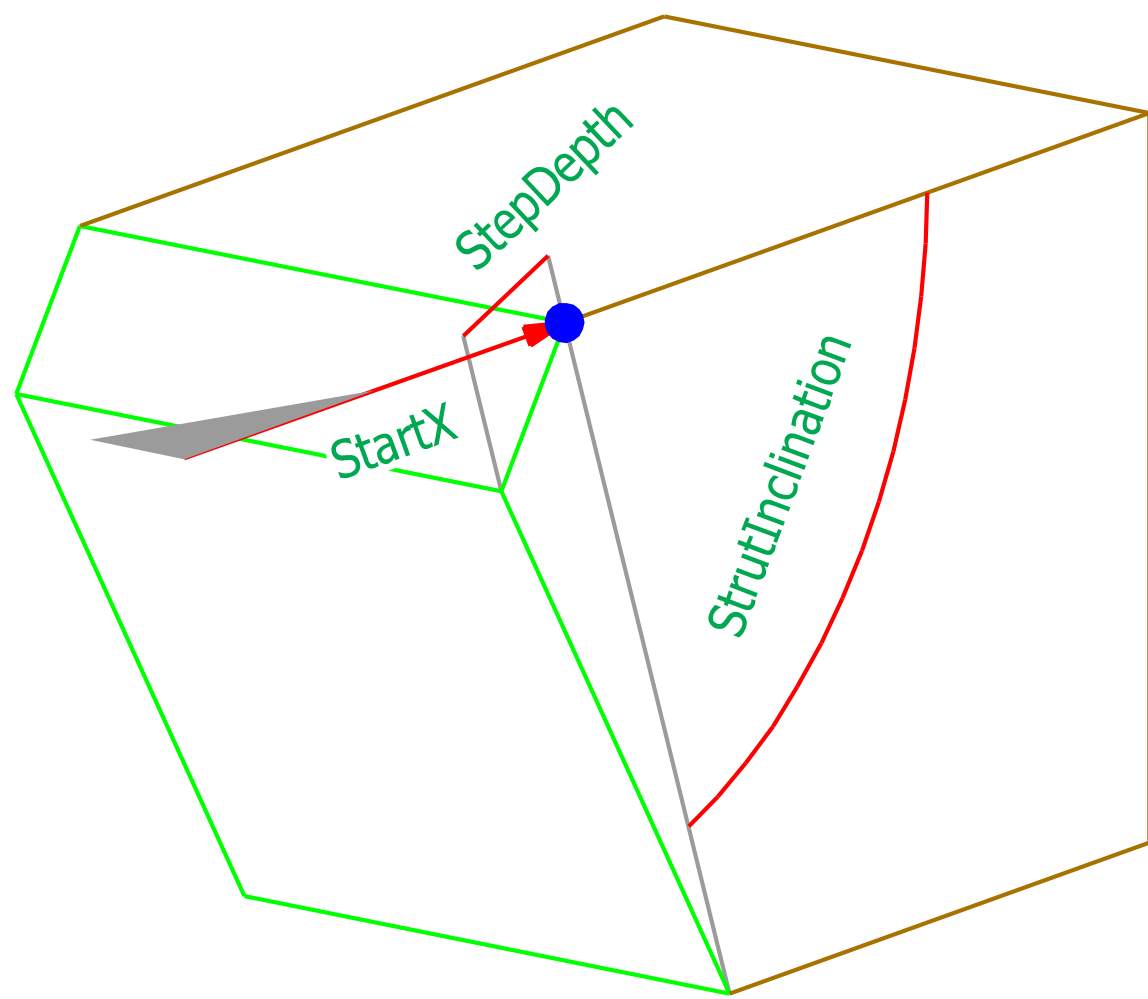
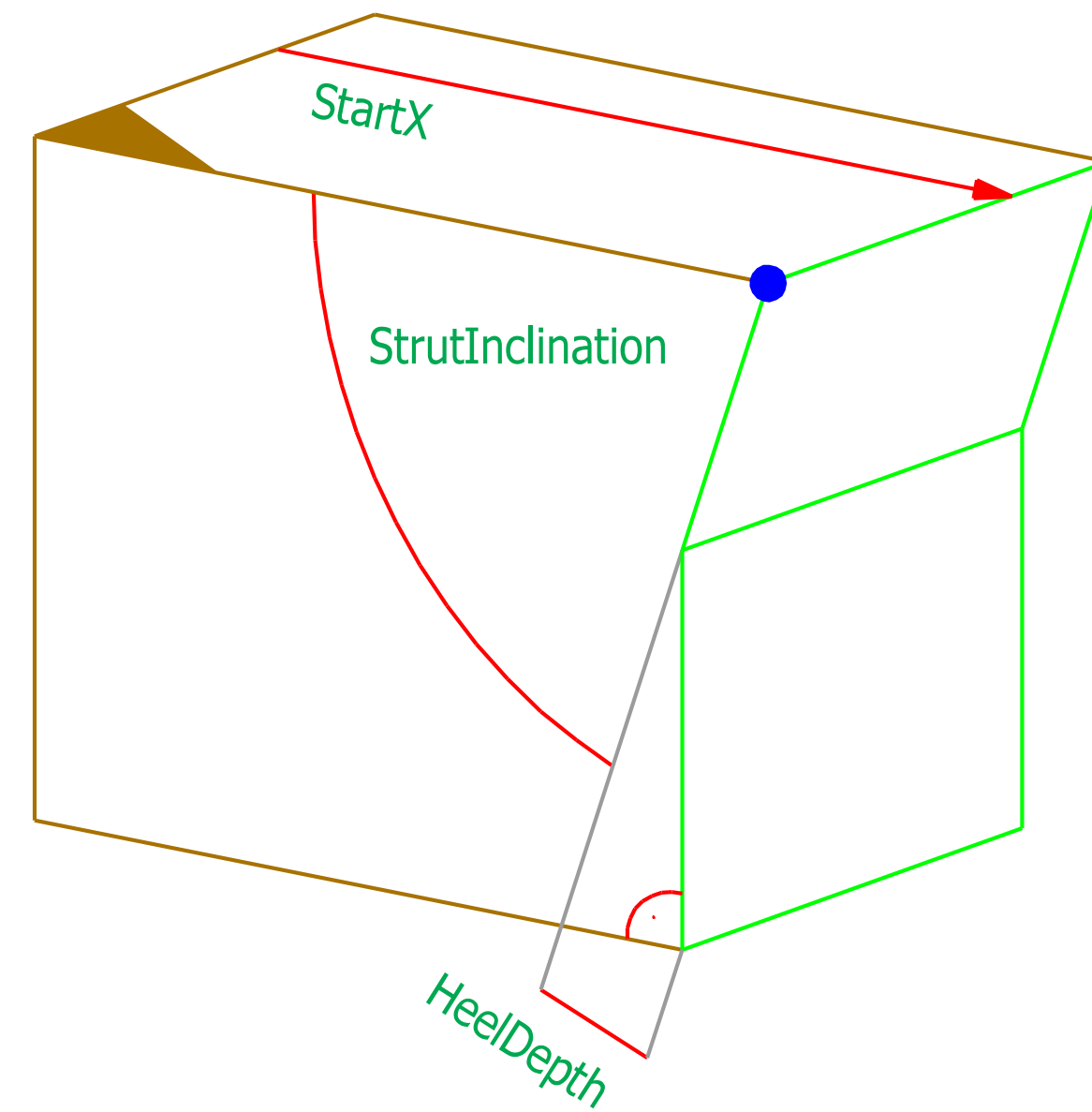
Tenon = no



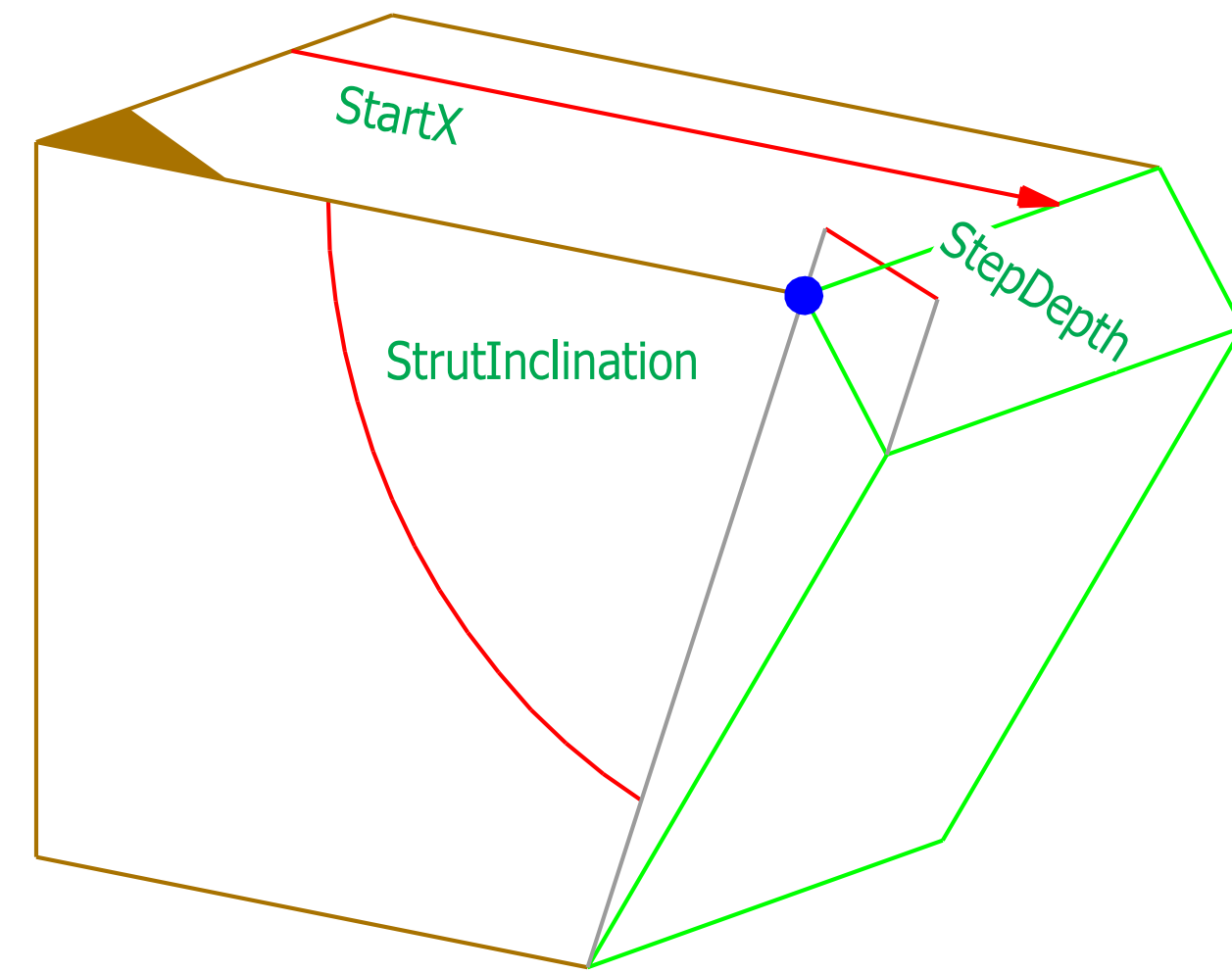
StepShape = double



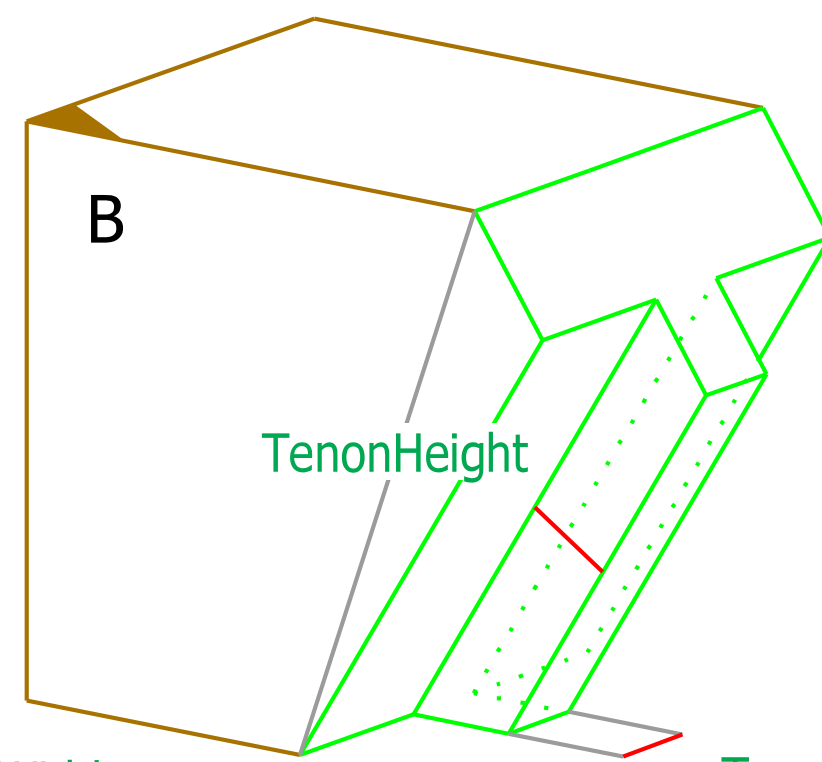
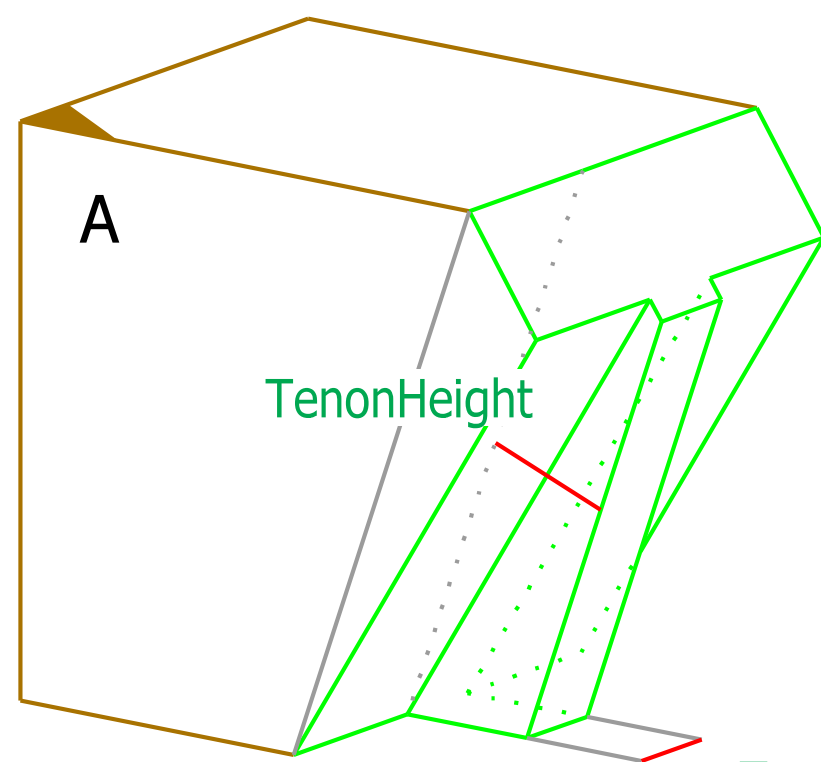
StepShape = step



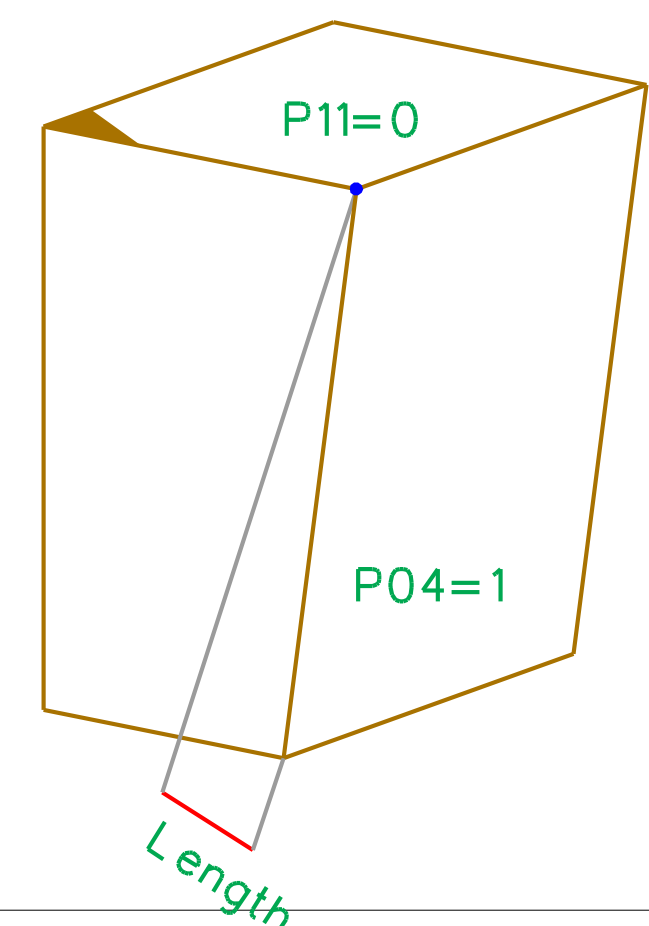
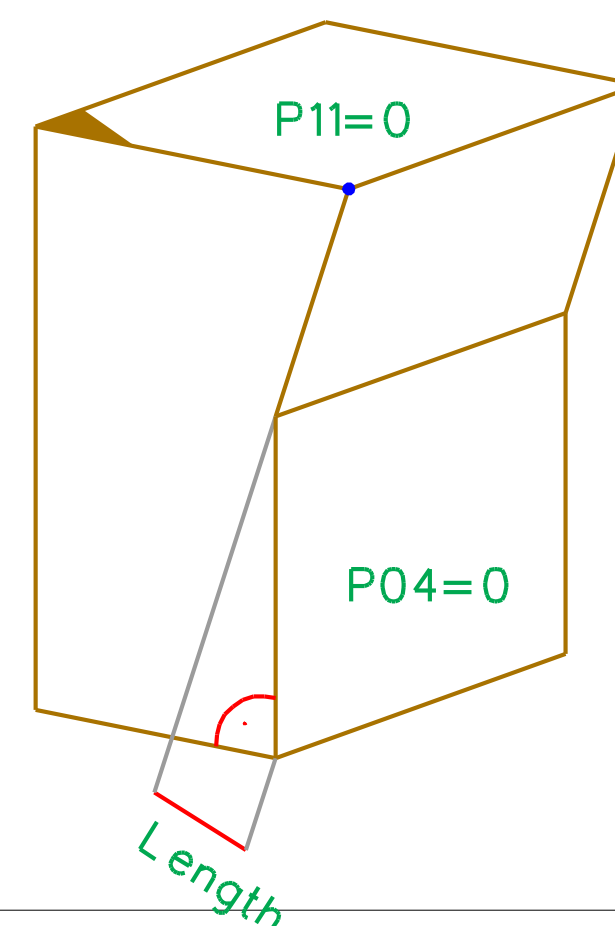
StepShape = heel



Tenon = yes



Which style (A or B) is used depends on the machine



## Parameters StepJoint

Name	Type	Default	Min	Max
Orientation	OrientationType		start	end
StartX	LengthPosType	0.0	-100000.0	100000.0
StrutInclination	AngleType		0.1	179.9
StepDepth	WidthType	20.0	0.0	50000.0
HeelDepth	WidthType	20.0	0.0	50000.0
StepShape	StepShapeType	double		
Tenon	BooleanType	no	no	yes
TenonWidth	LengthSType	40.0	0.0	1000.0
TenonHeight	LengthSType	40.0	0.0	1000.0

